BRAKEThrough Solutions: The Remote Braking System

Group 8

## Our Team



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# Pediatric Gait Trainer



# **Presentation Format**

- Development Process
  - > Construction, Logistics, Testing
- Deliverables Overview
- Product Description
- Live Demonstration
- Team Experience and Lessons

The braking system should be:

Safe and reliable

# Need Statements

- Can be activated from a distance
- Portable
- Vary braking force





"The client needs a **safe** and **reliable** remote braking system for his son's pediatric gait trainer. It can be **activated from a distance** to let him practice walking independently."

# Metrics

Metric	Units	Client Statements					
Functional Requirements							
Braking Distance Metres (m) The braking system is safe and reliable.							
Range of Transmission	Metres (m)	The braking system can be activated from a distance.					
Speed of Transmission	Seconds (s)	The braking system is safe and reliable.					
Activation Method	Remote	The braking system can be activated from a distance.					
Function	Versatility of braking system (Rating 1-5)	The system stops the trainer with controlled deceleration. The braking system functions in various common walking environments.					
	Non-Function	al Requirements					
Mass	Kilograms (kg)	The system is adaptable to multiple versions/models of gait trainers and users					
	Cons	straints					
Cost	CAD (\$)	100					
Battery/power life	Hours (h)	The braking system is durable and long-lasting.					

## Benchmarking and Ranking

Product and company	Importance (weight)	Rollator Brakes	Grillo Gait Trainer Brakes	R8 Crocodile Hand Brake	Rifton Pacer Gait Trainer: Rifton Casters
Activation Method	3	1	2	1	2
Function	2	3	2	2	1
Cost	1	3	2	2	1
Total		12	12	9	9

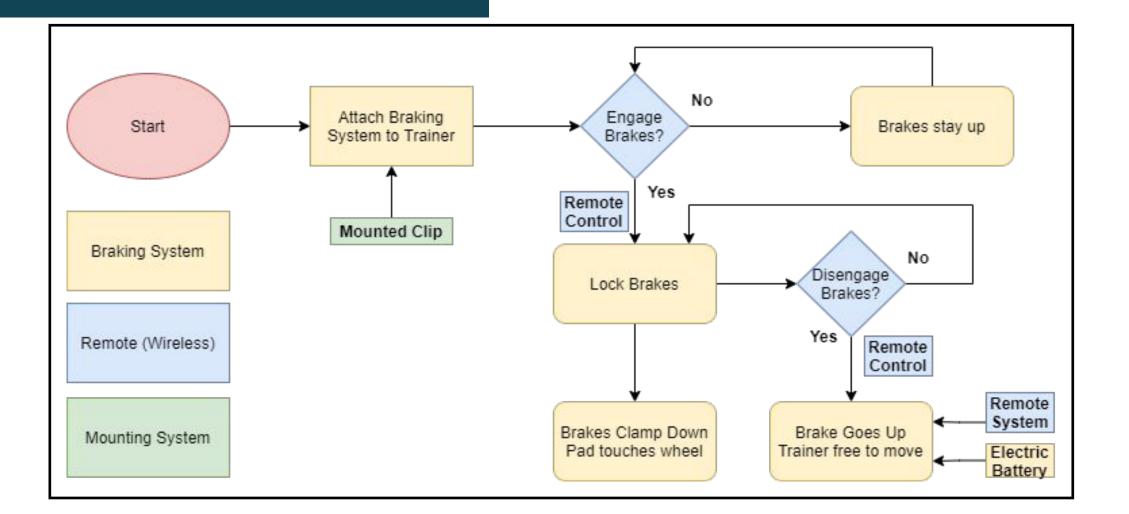
#### Target Specifications and Constraints

Design Specifications	Relation (=, < or >)	Value	Units	Verification Method				
Functional Requirements								
Braking Distance	<	Ideal: 1 Acceptable: 2	m	Testing				
Range of Transmission	<=	Ideal: 10 Acceptable: 8	m	Testing				
Speed of Transmission	<=	Ideal: 0 Acceptable: 500	ms	Testing				
	C	onstraints						
Cost	<	Ideal: 100 Functional: 150 (with permission)	CAD	BOM Estimation				
Battery/power life	>	Ideal: 12 Acceptable: 8	hours	N/A				
Non-functional Requirements								
Mass	<	Ideal: 3 Functional: 5	lbs	Measuring				

#### **Design Criteria**

Client Need Statements	Design Criteria
The braking system is safe and reliable.	Safety.
The braking system is durable and long-lasting.	Durability.
The braking system can be activated from a distance.	Remote braking.
The braking system is attachable and detachable while maintaining the trainer's state.	Portable.
The braking system functions in various common walking environments.	Environment versatility.
The system stops the trainer with controlled deceleration.	Gradient braking.

#### **Functional Decomposition**



	Member	Subsystem	Concept	Sketch	
	Tahmeed	Braking System	<ul> <li>Emergency manual brake</li> <li>Remote controlled piston</li> </ul>	Manual Brake Push down	
Conceptual Designs	Matt	Braking Controller	<ul> <li>Engage/disengage button</li> <li>Uses 2-way bluetooth communication</li> </ul>	Indicator Brake 1 Brake 2 Diengage Battery Status	
	Brad	Mechanical Braking System	<ul> <li>Does not rely on battery power</li> </ul>	Con Cast and Rows Eduction modes puells pin * and from provide the second state of t	

Conceptual Designs cont'd.

Member	Subsystem	Safety (4)	Remote	Gradient	Portability
Tahmeed	Braking System		Braking (3)	Braking (2)	(1)
	Braking System	1	1	2	3
Matt	Braking Controller	3	4	1	3
		1	1	1	1
Brad	Stopper Attachment	2	1	2	4
	Mechanical Braking System				
	Mounting	1	2	2	1
Elsa	Global Concept	1	2	2	1
	Global Concept	2	2	2	2

# Conceptual Designs cont'd.



### Client Meeting for First Conceptual Design

### **Client Cons:**

- Lack of Remote Disengagement
- Lack of Braking Speed control – pressure-sensitive button?

### **Client Pros**:

- Interested in wheel surface friction approach
- Not very strict with battery conservation

#### **Deliverable D**

### **Deliverable D Activities:**

- New design based on client feedback
- ITP Metrics
- Bill of Materials
- Team Name: **BRAKEthrough Solutions**

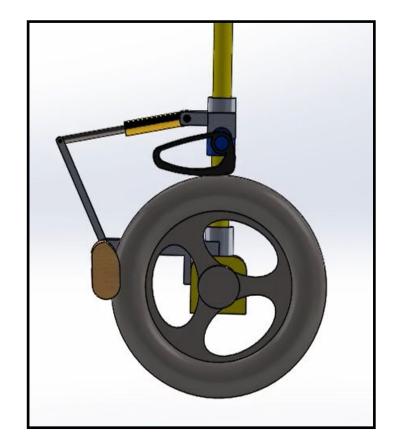


Item	Description	Quantity	Price	Source
Item	Description	(Approx.)	Price	Source
Aluminium Flat Bar	Used to make a mounting system for the brake.	3' (\$0.11/ft)	\$3.96	<u>Makerstore</u>
Micro Linear Actuator/Push Pull Solenoid	Used to engage and disengage brakes.	1	\$25-\$30	<u>Makerstore</u>
9V Battery	It's a battery!	1	\$1-\$4	Makerstore https://makerstore.ca hop
Bluetooth HC-05	Allows for bluetooth communication using Arduino	1	\$12.99	<u>MakerLab</u>
12V Battery	Again, it's a battery.	1	\$8.95	Amazon https://www.amazon a/Energizer-A23-GF 3AE-Alkaline-Batter §
Arduino Nano	Used for logic and communication.	2	\$8.00	MakerLab
Pushbutton	Digital Button	2 – 3	Free	Owned by multiple Team Members
Potentiometer/Pr essure Sensitive Button	Analog potentiometer dial for force selection.	1	Free	Owned by Tahmee
RGB LED	LED with ability to change colors for battery indication.	2	Free	Owned by multiple Team Members
Arduino Casing	Protects arduino	1	Free	3D Printed in L'Abb
Controller Casing	Protects arduino in controller	1	Free	3D Printed in L'Abl
Total			\$68.85 (Approx.)	

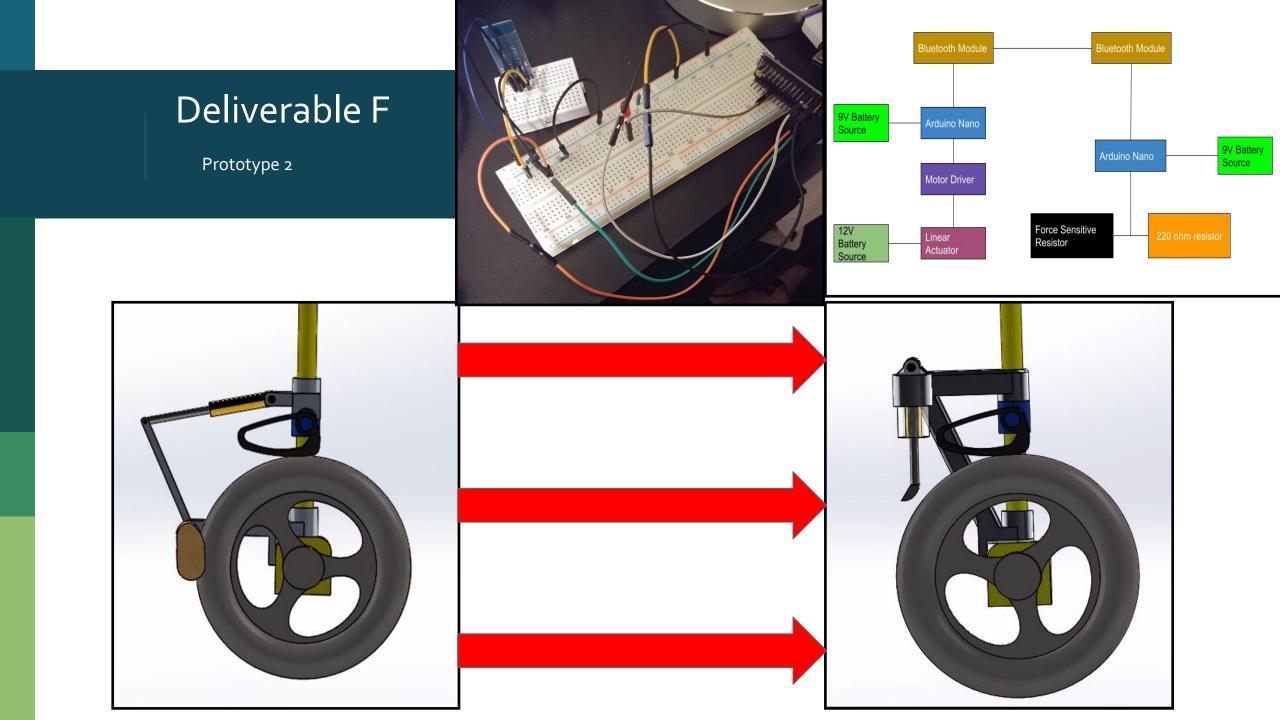
#### **New Braking Mechanism**

### "Angled Arm" Design:

- Uses Mechanical Advantage
- Avoids modifying the Reverse Stops
- Planned to pitch for next Client Meet



### **Also, Deliverable E Presentation!**



# Deliverable G - Business Model

Key Partners	Key Activities	Value Pro	opositions Relationships		Customer Segments																						
Accessibility-related Organizations	Manufacturing and selling of remote brakes for gait trainers	Balancing the safety with the independence for disabled people requiring gait trainers. Reaching the target market		with the independence for		with the independence for		with the independence for		with the independence fo		with the independence for		with the independence for		with the independence for		with the independence for		with the independence for		with the independence for		with the companies independence for Client feedback		Mostly indirect, through trainer companies or reviews Client feedback response plan	Parents of those with disabled children
Gait Trainer Companies	Key Resources Stores (online or physical) Resource available to gait trainer companies			Channels As accessories on already-existing trainers Available separately direct-to-consumer through private sales	Caretakers for the disabled requiring gait trainers																						
Cost Structure				Revenue Streams																							
Manufacturing Costs Marketing and Sales Development for Adaptability				Through gait trainer accessory Through direct-to-consumer pu Through investors																							

# Deliverable G - Economics

		Incomo (¢)	$C_{oct}(\mathfrak{k})$	Details	]			
		Income (\$)	Cost (\$)		Quarter	PV Income	PV Expenses	PV Profit (I - E)
Sales Reven	nue (3 years)	5,760,000		(\$400/unit*4800 units)*3 years	1	\$480,000	\$651,875	-\$171,875
Mat	terials		2,880,000	(\$200/unit*4800 units)*3 years		\$480,000	\$031,873	-\$1/1,6/5
Cost of C	Goods Sold		2,880,000		2	\$960,000	\$1,103,750	-\$143,750
Gross	s Profit	2,880,000			3	\$1,440,000	\$1,555,625	-\$115,625
			Operating Expenses		4	\$1,920,000	\$2,007,500	-\$87,500
	Ove	rhead	200,000	Fixed initial expenses	5	\$2,400,000	\$2,434,375	-\$37,375
	Shippiı	ng Costs	300,000	(\$21*4800 units/year)*3 years	6	\$2,880,000	\$2,861,250	\$18,750
	Elec	tricity	300,000		7	\$3,360,000	\$3,288,125	\$71,875
	Sal	aries	1.5 million	(10 Workers *\$50,000 annual)*3 years	8	\$3,840,000	\$3,715,000	\$125,000
	Equipment R	ental and Rent	112,500	(40ft by 40ft Space at \$1.50/ft^2, Also 3 mills at \$2900 each)*3 years	9	\$4,320,000	\$4,141,875	\$178,125
	Deprecia	tion Costs	30,000	(3 Years)	10	\$4,800,000	\$4,568,750	\$231,250
	Lo	ans	100,000	(Over all 3 years) (Paid back in first year)	11	\$5,280,000	\$4,995,625	\$284,375
Operatir	ng Income	337,500		(No income Tax)	12	\$5,760,000	\$5,422,500	\$337,500
Net I	Net Income							

## Income Statement

# **PV** Analysis

# Testing Our Design

Aspects Tested	Target	Observed	
Activation Range	10 meters	18.3 meters	
Braking Force	750 N (Given)	Sufficient	
Activation Time Delay	1 Second	0.5-1.0 Seconds	la.
Mount Stability	Firmly (No Budge)	Minute Movement	
Braking Distance	1 meter	1-2 meters	
Total Mass (1 brake unit)	2-3 lbs	5 lbs	
Battery Life	2.5 hours	2-3 hours	
<b>Cost (More of a Constraint)</b>	\$100	\$150	



Quantitative Qualitative

# LIVE DEMONSTRATION

### Trials and Tribulations

#### **Constraints**

### Tribulations

### Budget

### Changing client

requirements

### Lessons Learned and Future Work

#### **Lessons learned**

- Communication
- Organization

### **Future work**

- Second brake
- Soldered connections

#### Conclusion

- Many struggles and obstacles
- Ultimately: a success!
- Worthwhile learning experience for

### client-driven development

# Thanks for Listening!