# Project Deliverable EPresentation <br> Chelse Rose Vadakkeveettilan Hilariyos Vivethen Balachandiran Yassine Ouloum Laura Keryakes <br> Jiayi Ma 

## Agenda

| Customer Needs | Initial Project Plan |
| :--- | :--- |
| Benchmarking | Client Meet \#2 Feedback |
| Target Specifications | Development of Prototype |
| Concepts | Current Prototype \& Testing |
| Decision matrix | Client Meet \#3 and Future |
| Feasibility Study | Plans |

## What is our project?

- Product that measures athlete performance
- Users: athletes, coaches or anyone looking to monitor or improve their performance



## Client Needs

Key Takeaways from Client Meet 1:

1. The product detects and collects measurable data related to sports performance.
2. The product has no effect on the user's ability to perform.
3. The product analyzes and categorizes data and outputs it to a user-friendly centralized platform.
4. The product is lightweight, portable, durable and waterproof.


## Problem Statement

"Athletes and coaches playing tenifis are looking for a portable, durable and waterproof product that effectively measures theirperformance and outputs it via a user-friendly platform that allows constant comparison of statistics amongst themselves and their team."

## Benchmarking - Current Products in the Market

Watch Tracker - for Running


Easy set up Centralization of data on app App stores daily totals for up to 30 days Waterproof Durable Adaptable to
parasports


## GPS Performance Tracker - for Soccer (STATSports)



Figure 3.a

3.b

- Easy set up
- Centralization of data on app
- Waterproof
- Durable
- Adaptable to parasports

Installed Club Sensors (Garmin Approach CT-10)

- Easy set up

Data sorting included

- Centralization of data on app
- Waterproof
- Durable



## Target Specifications

| Metric | Unit | Marginal <br> value | $\frac{\text { Ideal }}{\text { value }}$ | Reason for choices |
| :--- | :--- | :--- | :--- | :--- |
| Speed measurable | $\mathrm{m} / \mathrm{s}$ | $0-118.33$ | $0-150$ | Cover the world's maximum badminton hitting <br> speed to avoid unexpected situations. |
| Impact force <br> measurable | N | $>280$ | $>300$ | Simplified estimation done according to the <br> maximum and minimum speed measurable in <br> Metric \#1 Conducted through testing (Nagwa). |
| Weight | g | $>80$ | $80<$ | Light and convenient; It should be a seamless <br> device. |
| Size of device | cm 3 | $<9$ | Small and fits the racket. |  |
| Life expectancy | Years | $>1$ | $>3$ | The battery life is long enough to be used <br> during multiple seasons and the battery is <br> replaceable. |

## Decision matrix

| Selection criteria | Racket: Detachable | Racket: Built-in | Gloves |
| :---: | :---: | :---: | :---: |
| Speed measurable | 5 | 5 | 4 |
| Impact force <br> measurable | 5 | 5 | 4 |
| Weight | 5 | 2 | 4 |
| Size of device | 4 | 1 | 3 |
| Life expectancy | 3 | 3 | 4 |
| Total score |  | 16 | 19 |

Therefore, the Group Concept will be a detachable sensing system mounting on a tennis racket.

## Strengths:

- Inexpensive and Affordable
- Lightweight and Compact
- Sensitive and Accurate
- Data visualization


## Weaknesses:

- Difficult installation/ disassembly process
- Few target clients
- Short product development period


## TELOS:

> Technical: Technical support in software, but still lack the knowledge of hardware.
$>$ Economic: R\&D expenses slightly exceeded expectations.
$>$ Legal: Make sure developer-friendly tools and low-cost deployment.
$>$ Operational: Rational task allocation and On-chain governance.
> Scheduling: Deadline is Nov. 30, and a three-month period is short for R\&D work.

## Group Goneents



Initial Group Concept

## Client Meet \#2

- Feedback for Design Improvement
- Preferred use of bluetooth chips Advised use of more sensors positioned around the racquet
- An advertisement or an application alongside the product.
O Output of data to the user should be continually updated.
- Data is outputted in a user-friendly manner


## Group Concept After Client

 Meet 2

## Project Plan



## Project Plan

X: 1 week
$\square$ : Milestone
Issues encountered:

- Task \#4: Sickness
- Task \#4: Uncertainty about final design
- Task \#5: Review of final design


## Project Plan



## Project Plan

X: 1 week<br>: Milestone

Issues expected:

- Task \#6: Delay in components arrival
- Sickness or member absence


## Prototype 1

Using Gyroscope and Accelerometer

- Acceleration Input

We want:

- Peak Velocity (at what position \& time)



## How does it work?



Create a loop


Calculate
current velocity


If it's higher
replace it



| Time To Test! | Acceleration | 0 | +2 | +3 | -1 | +1.5 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  | Time | 0 | 1 | 2 | 4 | 5 |
|  |  |  |  |  |  |  |

Kinematic Equation: $\mathbf{V}_{\mathrm{f}}=\mathrm{V}_{\mathrm{i}}+\mathrm{a} * \Delta \mathrm{t}$


Initialize variables
Set $V_{i}, V_{f}, a, t$, peakV $=0$

## 2

Calc current velocity ( $\mathrm{V}_{\mathrm{f}}$ )
Use data table and equation

$$
v_{f}=0+(0 * 0)=0
$$

| Time To Test! | Acceleration | 0 | +2 | +3 | -1 | +1.5 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  | Time | 0 | 1 | 2 | 4 | 5 |
|  |  |  |  |  |  |  |

Kinematic Equation: $\mathbf{V}_{\mathrm{f}}=\mathrm{V}_{\mathrm{i}}+\mathrm{a} * \Delta \mathrm{t}$


Change peakV and $V_{i}$ ?
$\mathbf{V}_{\mathrm{f}}=\mathbf{0}$, so peakV still 0
$V_{i}=V_{f}=0$


And repeat...
For all data table values

| Time To Test! | Acceleration | 0 | +2 | +3 | -1 | +1.5 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  | Time | 0 | 1 | 2 | 4 | 5 |

Kinematic Equation: $\mathbf{V}_{\mathrm{f}}=\mathrm{V}_{\mathrm{i}}+\mathrm{a} * \Delta \mathrm{t}$

Row 2:
$\mathrm{V}_{\mathrm{f}}=0+(2 * 1)=2 \quad \mathrm{~V}_{\mathrm{f}}=2+(3 * 1)=5$ peakV $(0)<V_{f}(2) \rightarrow$ peakV $(2)<V_{f}(5) \rightarrow$
peakV = 2
peakV = 5
$V_{i}=V_{f}=5$

$$
v_{i}=v_{f}=3
$$

Row 5: $\quad \mathbf{V}_{\mathrm{f}}=3+\left(1.5^{*} 1\right)=4.5$ peakV $(5)>V_{f}(4.5) \rightarrow$ peakV $=5$

## Potential Limitations

- Requires high frequency measurements
$\square$ Assuming constant acceleration between intervals
- $X, Y, \& Z$ axis may make things more complex


## Next Steps

## Objectives:

- Update Prototype 1
- Prototype 2
- Final Prototype


