



Hand Grip

By: Nishchal, Doga, Liam and Hongjian

Why a hand grip device?



Client needs:



- The client wants to be able to hold small objects just as needle
- The client mentioned a project she was interested in with three-fingers and an arm support but did not hear back from them
- The client has not tried a hand grip glove before
- The client does not like compression glove, she prefers the glove to be of medium or large size

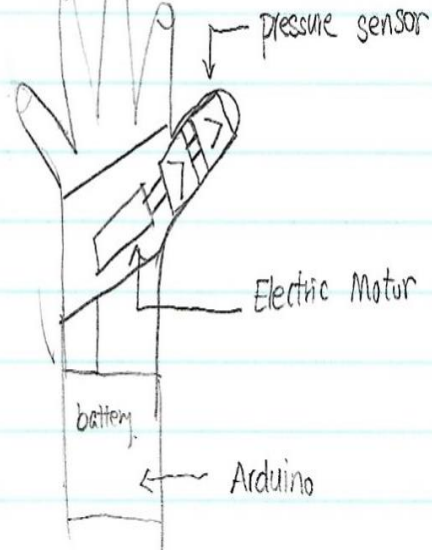
Our Problem Statement:



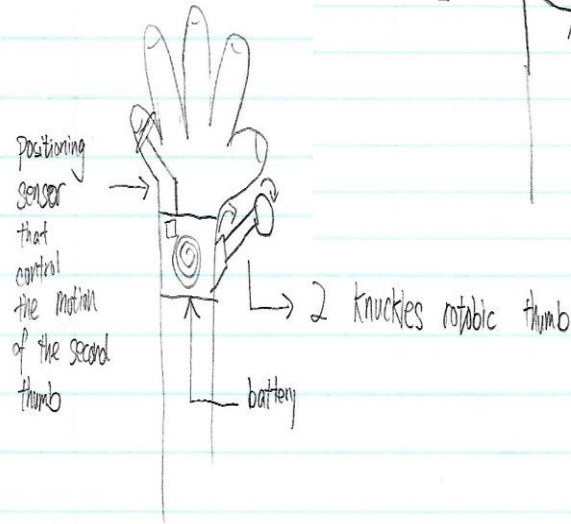
“To design a comfortable, compact device that will help the client perform gripping and pinching motions.”

Sketches (Hongjian)

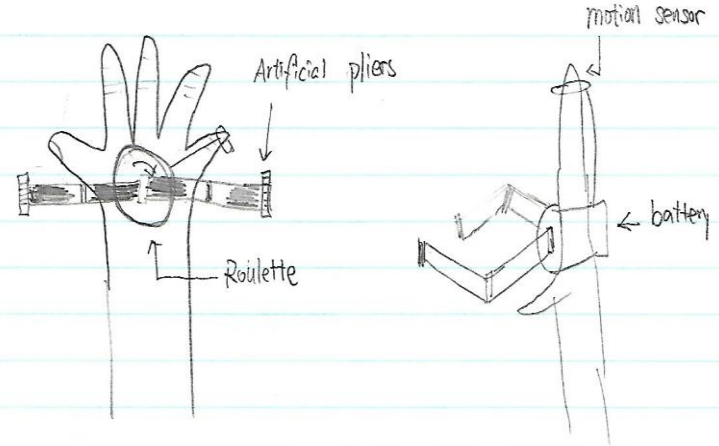
Soln 1.



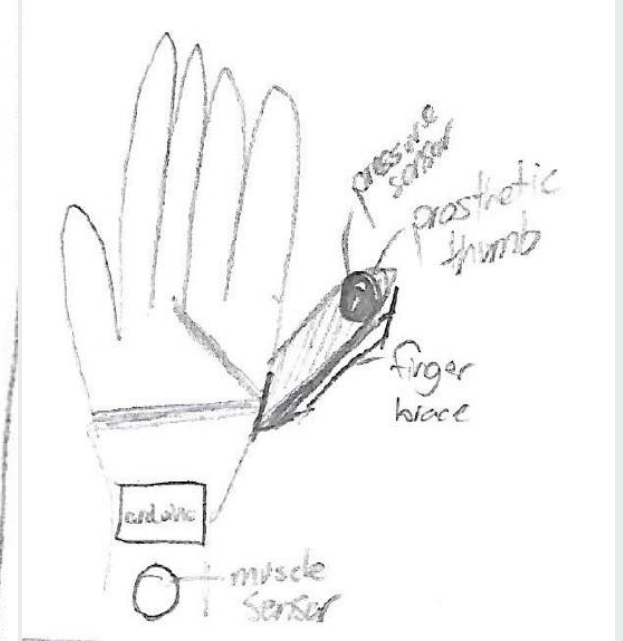
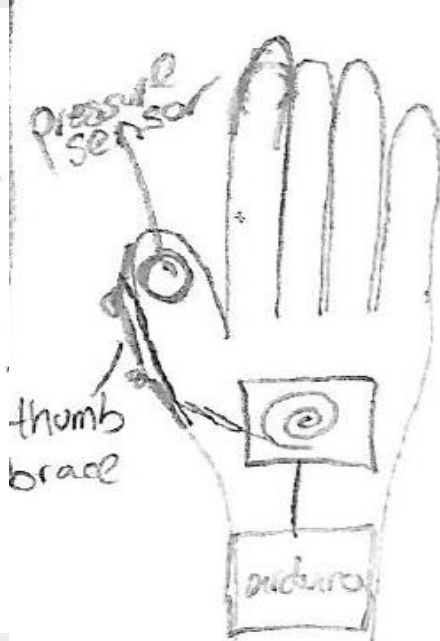
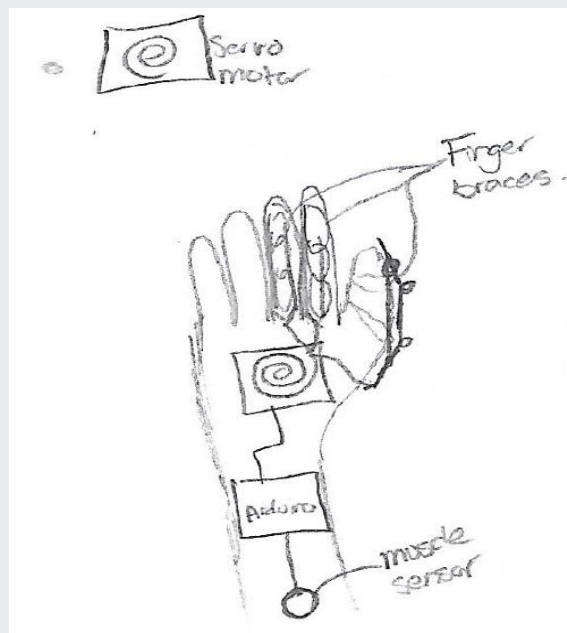
Soln 2:



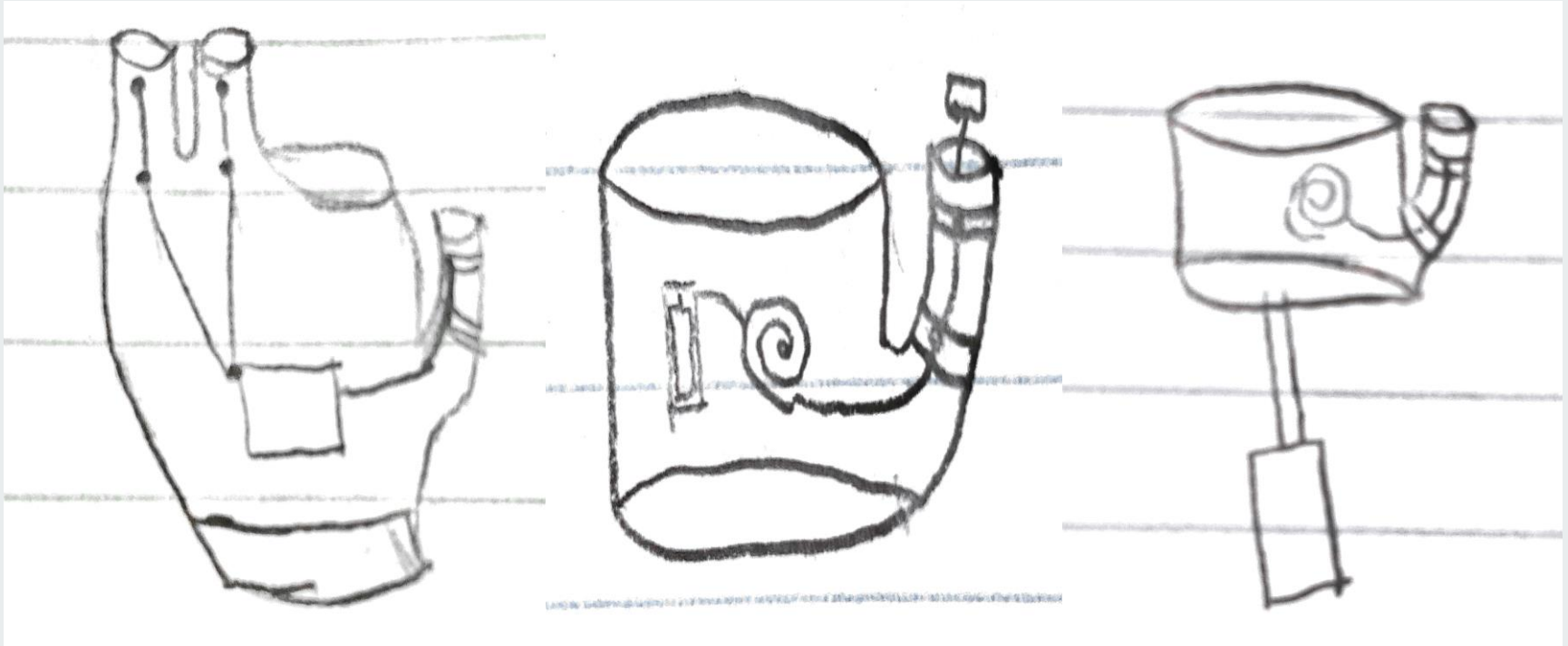
Soln 3



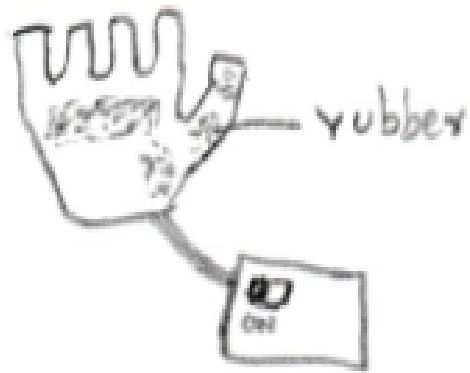
Sketches (Liam)



Sketches (Doga)



Sketches (Nishchal)



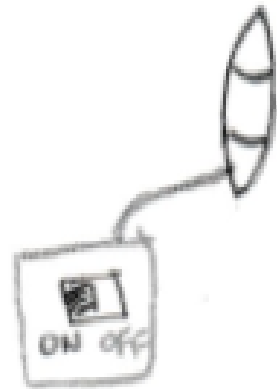
manual grip

Front:






robotic glove

Back:



robotic thumb

Benchmarking

Benchmarking projects	Technology	Price	Sizing	Target Client	Picture of the Product	Website
Saebo Glove	Manual	\$559 CAD	Small, Medium, Large	Neurological and orthopedic injuries patients		https://www.saebo.com/saeboglove/
The Third Thumb	Bluetooth-pressure sensors	N/A	One size	Everyone		https://www.daniclodedesign.com/thethirdthumb
Gripit	Manually	N/A	circular diameter: 30mm Height: 20mm	Patients with spinal cord injuries.		https://www.wevolver.com/wevolver-staff/gripit-master/blob/Overview.md

Metrics



Metrics Number	Importance	Metrics	Units
1	2	Mass	g
2	5	Minimum Gripping strength	kg
3	4	Device Size	size
4	3	Battery Life	hours
5	1	Water Resistance	bars
6	1	Wireless Charging	qi
7	4	Manufacturing Cost	\$CAD
8	4	Time taken to assemble/ disassemble	minutes
9	2	Instills Pride	subjective

Target Specifications (Part 1)



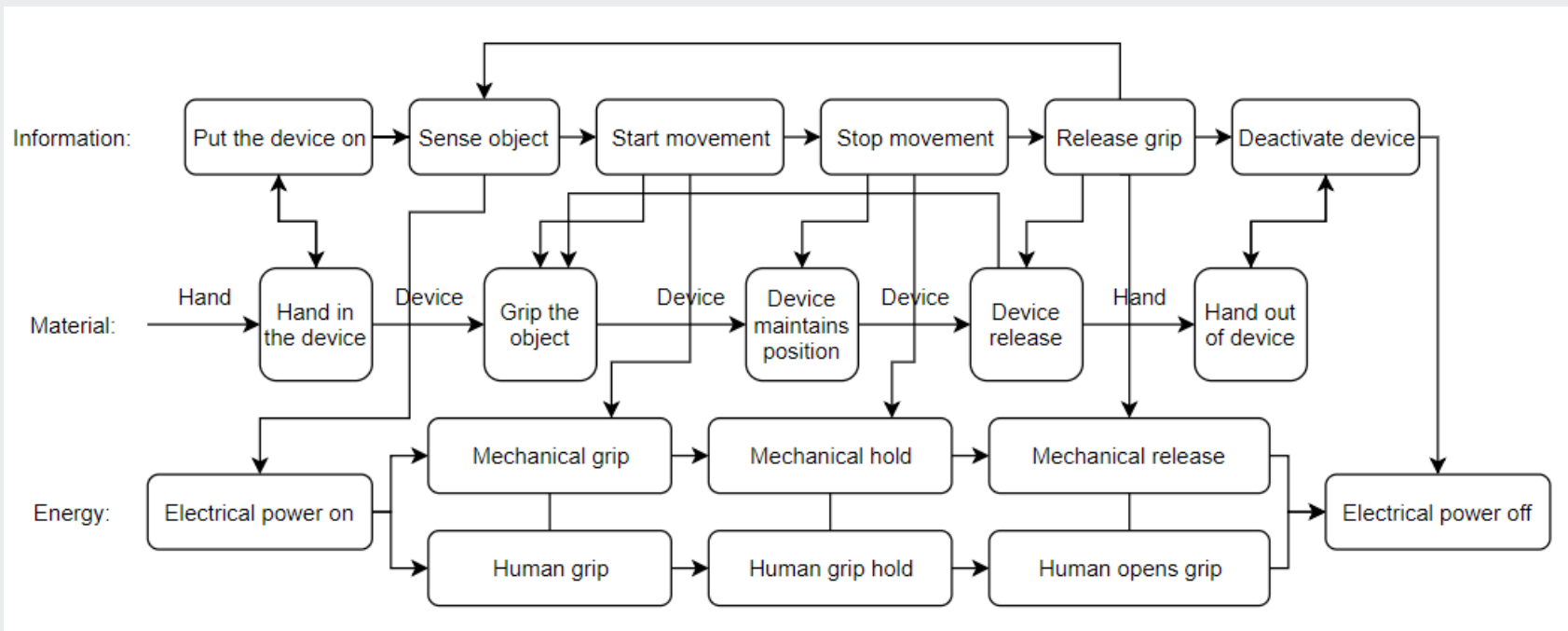
Metrics Number	Metrics	Units	Acceptable Value	Ideal Value	Reason
1	Mass	g	<500	<300	The product needs to be as light as possible. Boxing gloves weigh 250g on average.
2	Minimum Gripping strength	kg	>15	>20	This is the average gripping strength.
3	Device Size	size	= large	= medium	The client prefers medium or large glove size.
4	Battery Life	hours	>3	>6	The client will use this product for a long duration.
5	Water Resistance	bars	no	yes	Product might come in contact with water.

Target Specifications (Part 2)



Metrics Number	Metrics	Units	Acceptable Value	Ideal Value	Reason
6	Wireless Charging	qi	no	yes	Product will be able to recharge quickly without much effort.
7	Manufacturing Cost	\$CAD	<100	<90	Competitive prices have to be lower than the competitions'.
8	Time taken to assemble/ disassemble	minutes	<2	<1	Product is easily removable and wearable.
9	Instills Pride	subjective	a bit	a lot	Meets requirements and satisfies customer needs.

Functional Decomposition



Sketch:

Front side:



Back side:



Thumb:



Side view:



index:

join +

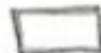
rubber

motor

plate

string

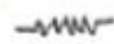
arduino



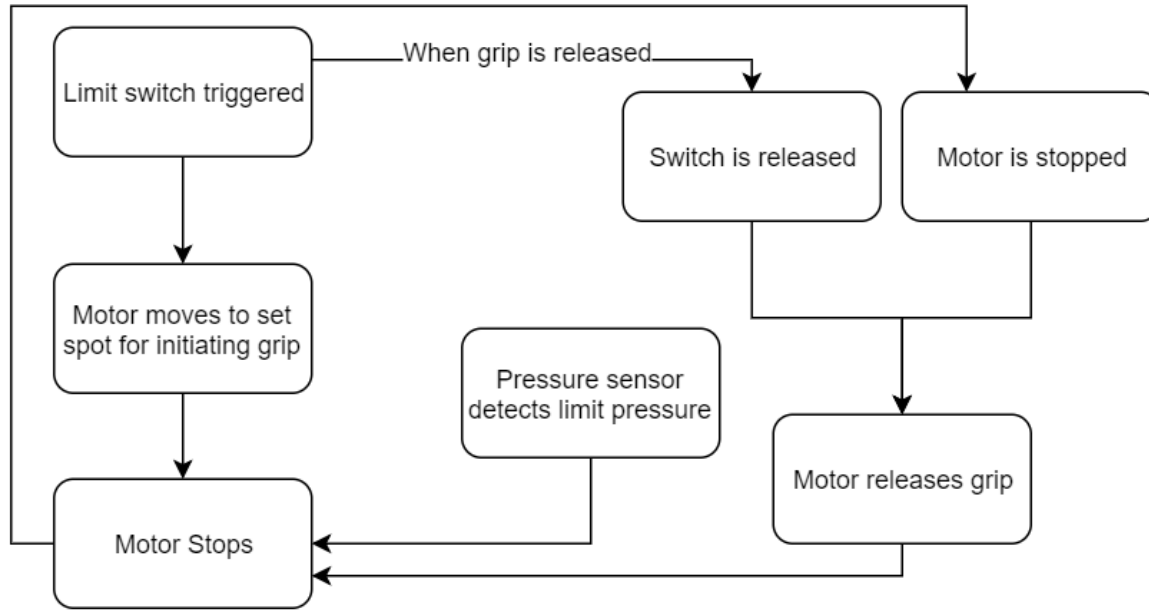
battery slot

wire

spring



Software Design



Grip prototype I



Bill of Materials



- On budget of \$100 for the project
- Many parts can be found or made for free

Part Name	Description (Identify prototype #)	Quantity	Unit Costs (\$CAD)	Extended Cost (Qty x \$)	Actual Cost (Qty x \$)
Push Button	A button to read a finger grip motion from the little finger and the right finger	2	4.95	9.90	9.90
Glove	To house the device and hold it onto hand of client	1	15.00	15.00	15.00
Servo motor	To spool strings used to activate fingers/thumb	1	30.00	30.00	30.00
Arduino Nano	Microcontroller to control the device	1	22.00	22.00	22.00

String	To help manipulate the plastic parts and cause gripping power	#	5.00	5.00	5.00
Wires	To wire the device to the arduino	#	11.95	11.95	0.00
PLA 3D printer filament	For various parts to manipulate the hand grip	#	Free	Free	0.00
Rubber pads	Provides extra grip in the palms	#	3.45	3.45	3.45
Battery pack	Holds batteries to power device	1	5.00	5.00	5.00
Battery	To power up the device	1	5.00	5.00	5.00
Spring	To execute on/off of the push button	2	0.86	1.72	Free
Elastic String	To execute on/off of the push button	1	0.40	0.40	Free
Needle	To weave parts on the glove	1	0.26	0.26	Free
Thread	To weave parts on the glove	1	0.10	0.10	Free

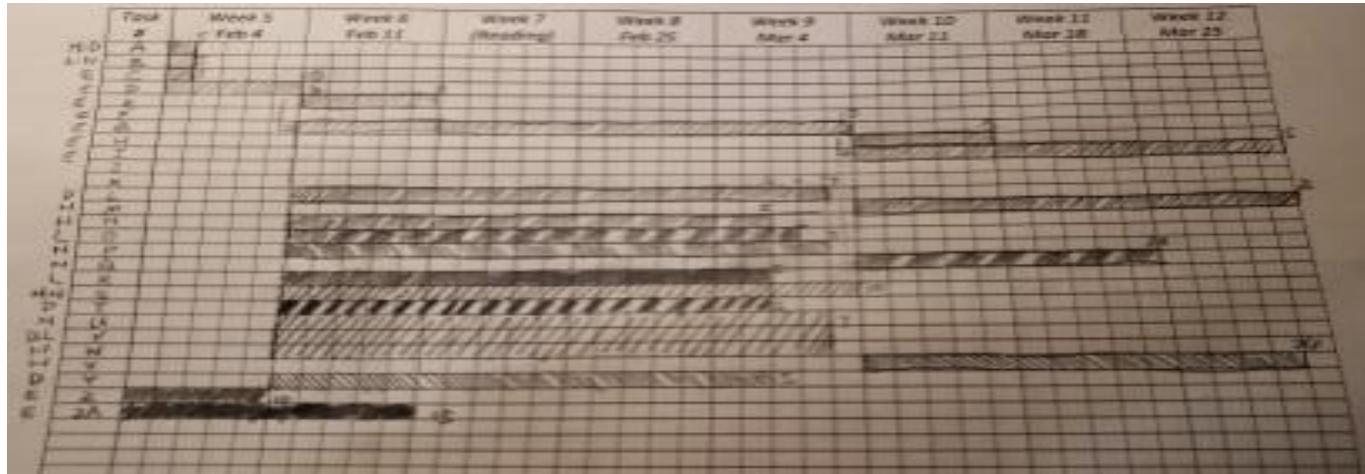
Prototype 1 Feedback



- Overall satisfied with the low level prototype
- Worried about the size of the device on her hand
- Ensured a breathable fabric would be used with the glove
- Ensured we knew her thumb didn't necessarily move/work the same way ours do

Plans for next Client Meet

- Functional prototypes for the different parts of the device
- Solidworks modelling of the device



Plans moving forward

- Independent learning
- Organization
- Time management
- Never give up!



References



<https://www.saebo.com/saeboglove/>

<https://www.daniclodedesign.com/thethirdthumb>

<https://www.wevolver.com/wevolver.staff/gripit./master/blob/Overview.md>

<http://www.calleenwilder.com/spirituality/powerful-mudras/>

<https://www.theprboutique.com/think-outside-the-box/>